

# KNX S1-B2 230 V

## **Multifunctional actuator**

# Technical specifications and installation instructions

Part number 70380





## 1. Description

The **KNX S1-B2 230 V actuator** with integrated façade controller has a multi-function output, a push button pair and control LEDs. Either a drive with Up/Down control (blinds, awnings, shutters, windows) or two switched devices (On/Off for light and ventilation) can be connected at the output. The drives and devices connected are operated directly at the **KNX S1-B2 230 V** and via hand switches.

Automation is specified externally or internally. Internally, there are numerous options available for blocking, locking (e.g. master-slave) and priority definitions (e.g. manual-automatic). Scenes are saved and called up via the bus (scene control with 16 scenes per drive).

Two binary inputs are used either for direct operation (e.g. hand switches) or as bus switches (or also for e.g. alarm notifications). The desired behaviour is defined precisely through selection of the response times in Standard, Comfort or Deadman mode.

#### **Functions:**

- 1 Multi-function output for a 230 V drive (shades, windows) or for connecting two switched devices (light, fan)
- Switch panel with switch pair and status LEDs
- 2 binary inputs for use as hand switches or as bus switches with variable voltage (6...80 V DC, 6...240 V AC)
- Automatic runtime measurement of the drives for positioning (incl. fault reporting object)
- Position feedback (movement position, also slat position for shutters)
- Position storage (movement position) via 1-bit object (storage and call-up e.g. via buttons)
- Control via internal or external automation functions
- Integrated shade control for each drive output (with slat tracking according to sun position for shutters)
- Scene control for movement position with 16 scenes per drive (also slat position for shutters)
- Mutual locking of two drives using zero position sensors prevents collisions e.g. of shade and window (master-slave)
- Blocking objects and alarm reports have different priorities, so safety functions always take precedence (e.g. wind block)
- Manual or automatic priority setting via time or communication object

Configuration is made using the KNX software ETS. The **product file** can be downloaded from the Elsner Elektronik homepage on **www.elsner-elektronik.de** in the "Service" menu.

## 1.1. Technical specification

Housing	Plastic	
Colour	White	
Assembly	Series installation on mounting rail	

Protection category	IP 20	
Dimensions	approx. $53 \times 88 \times 60 \text{ (W} \times H \times D, mm),$ 3 dividing units	
Weight	approx. 170 g	
Ambient temperature	Operation -20+70°C, storage -55+90°C	
Ambient humidity	max. 95% RH, avoid condensation	
Operating voltage	230 V AC, 50 Hz	
Power consumption	Operation max. approx, 1.2 W	
Power	on bus: 10 mA	
Output	1 x Output with 2 connections for drive Up/Down or 2 devices, 230 V (PE/N/1/2), in total max. 8 A and max. 4 A per connection	
Inputs	2 × binary inputs, universal voltage (680 V DC, 6240 V AC)	
Max. cable length Binary inputs	50 m	
Data output	KNX +/- bus plug-in terminals	
BCU type	Integrated microcontroller	
PEI type	0	
Group addresses	max. 1024	
Assignments	max. 1024	
Communication objects	130	

The product is compliant with the provisions of EU guidelines.

## 2. Installation and commissioning

## 2.1. Installation notes



Installation, testing, operational start-up and troubleshooting should only be performed by an electrician.



#### **DANGER!**

#### Risk to life from live voltage (mains voltage)!

There are unprotected live components within the device.

- VDE regulations and national regulations are to be followed.
- Ensure that all lines to be assembled are free of voltage and take precautions against accidental switching on.
- Do not use the device if it is damaged.
- Take the device or system out of service and secure it against unintentional use, if it can be assumed, that risk-free operation is no longer guaranteed.

The device is only to be used for its intended purpose. Any improper modification or failure to follow the operating instructions voids any and all warranty and guarantee claims.

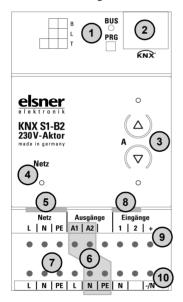
After unpacking the device, check it immediately for possible mechanical damage. If it has been damaged in transport, inform the supplier immediately.

The device may only be used as a fixed-site installation; that means only when assembled and after conclusion of all installation and operational start-up tasks and only in the surroundings designated for it.

Elsner Elektronik is not liable for any changes in norms and standards which may occur after publication of these operating instructions.

## 2.2. Device design

The device is designed for series installation on mounting rails and occupies 3U.



- 1) Programming LED and programming buttons (PRG)
- 2) Bus terminal slot (KNX +/-)
- 3) Switch pair Up/Down and LEDs
- Mains LED (Power), mode status display. Siehe "Display of operating status by the power supply LED" auf Seite 6.
- 5) Operating voltage input 230 V AC L/N/PE
- 6) Output A1 A2: "Up"-"Down" respectively "Device1"-"Device2", max. 4 A
- All terminals L, N, PE of the lower connection strip are bridged internally with "Main L, N, PE".
- 8) Binary inputs 1-2
- Internal auxiliary voltage + 24 V DC. Only for binary inputs! Do not assign any external voltage!
- 10) -/N for external auxiliary voltage (6...80 V DC, 6...240 V AC)



A mix of different auxiliary voltages for the binary inputs is not permitted.

## 2.2.1. Display of operating status by the power supply LED

Behaviour	Colour	
То	Green	Normal operation. Bus connection/bus voltage present.
Flashes	Green	Normal operation.  No Bus connection/bus voltage present.
То	Orange	Device starts or is programmed via the ETS.  No automatic functions are executed.
Flashes	Green (on), Orange (flash- ing)	Programming mode active.

## 2.2.2. Status display by the channel LEDs

Behaviour	LED	
То	top	Drive in top end position/device on.
То	bottom	Drive in bottom end position/drive on.
Flashes slowly	top	Drive moves up.
Flashes slowly	bottom	Drive moves down.
Flashes quickly	top	Drive in top end position, barrier active.
Flashes quickly	bottom	Drive in bottom end position, barrier active.
Flashes quickly	both simultane- ously	Drive in intermediate position, barrier active.
Extend	both	Drive in intermediate position.
Flashes	both alternately	Automatic runtime determination error.  If the drive can be moved, drive it into the end position by hand (drive in/drive out completely or open/close) in order to restart the runtime determination.  If the drive cannot be moved, check the connections.
"Run light" above all LEDs	all channels	Incorrect application version was loaded. Use the version compatible with the device!

## 2.3. Notes on mounting and commissioning

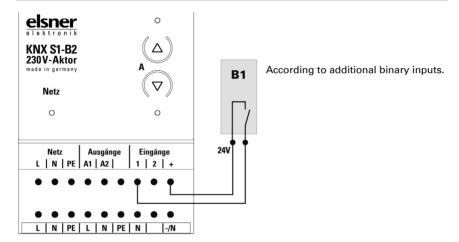
Device must not be exposed to water (rain). This could result in the electronic being damaged. A relative air humidity of 95% must not be exceeded. Avoid bedewing.

After the bus voltage has been applied, the device will enter an initialisation phase lasting a few seconds. During this phase no information can be received or sent via the bus.

For KNX devices with safety functions (e.g. wind or rain blocks), it is important to set up periodical monitoring of the safety objects. The ideal ratio is 1:3 (example: if the weather station sends a value every 5 minutes, the actuator must be configured for a monitoring period of 15 minutes).

## 2.4. Connecting example for binary inputs

### 2.4.1. Using the internal auxiliary voltage of the actuator



## 2.4.2. Using an external auxiliary voltage

