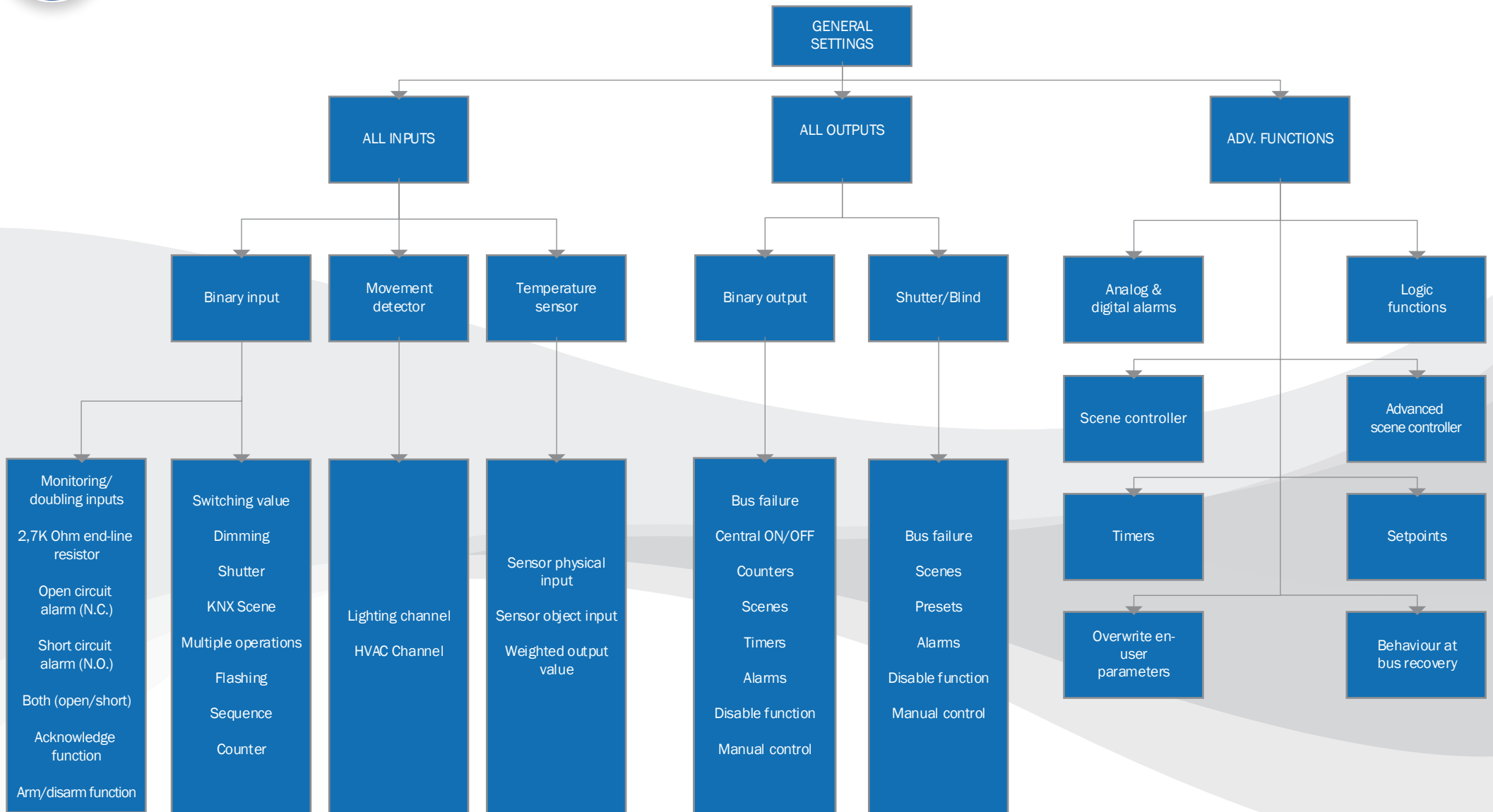
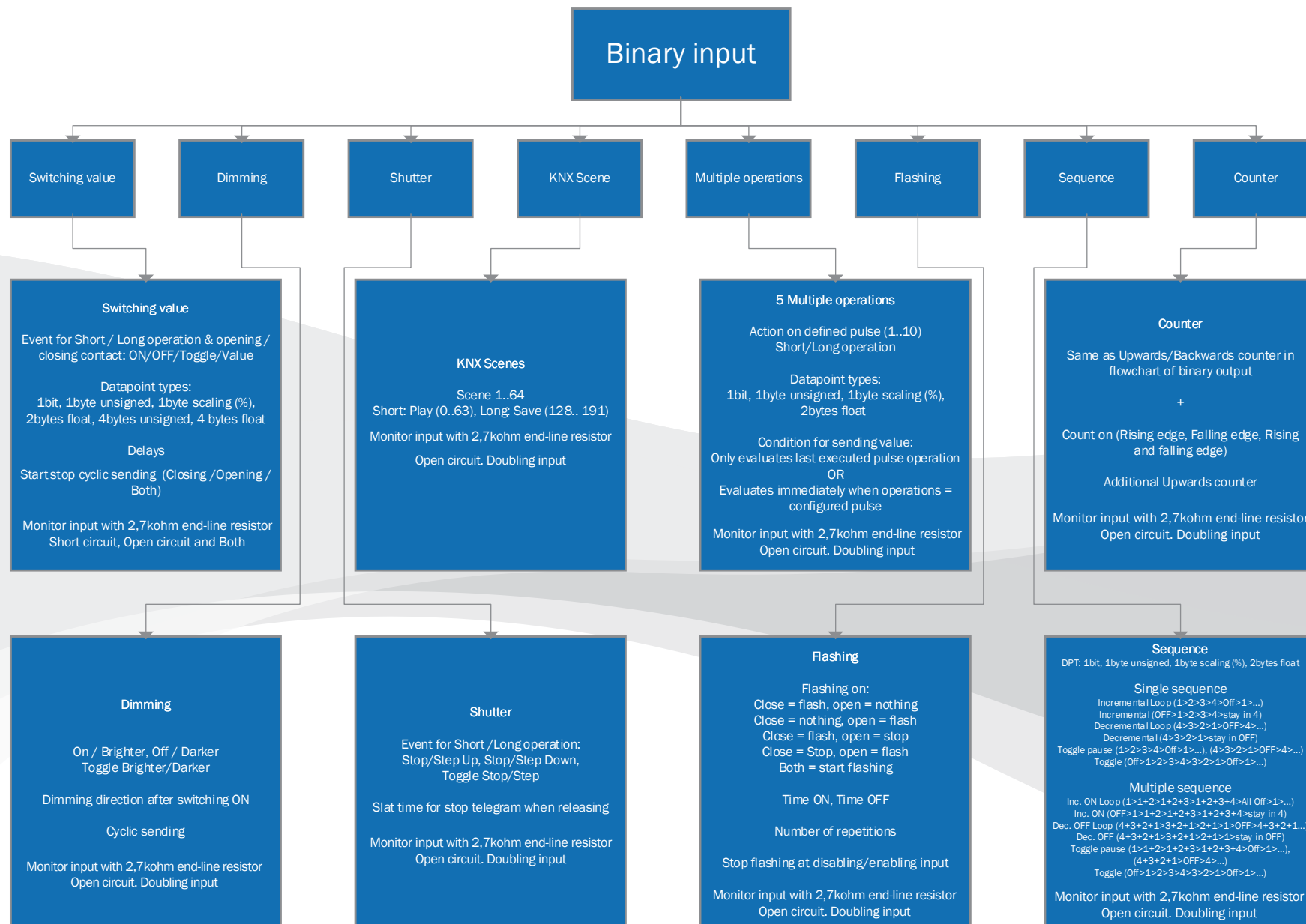
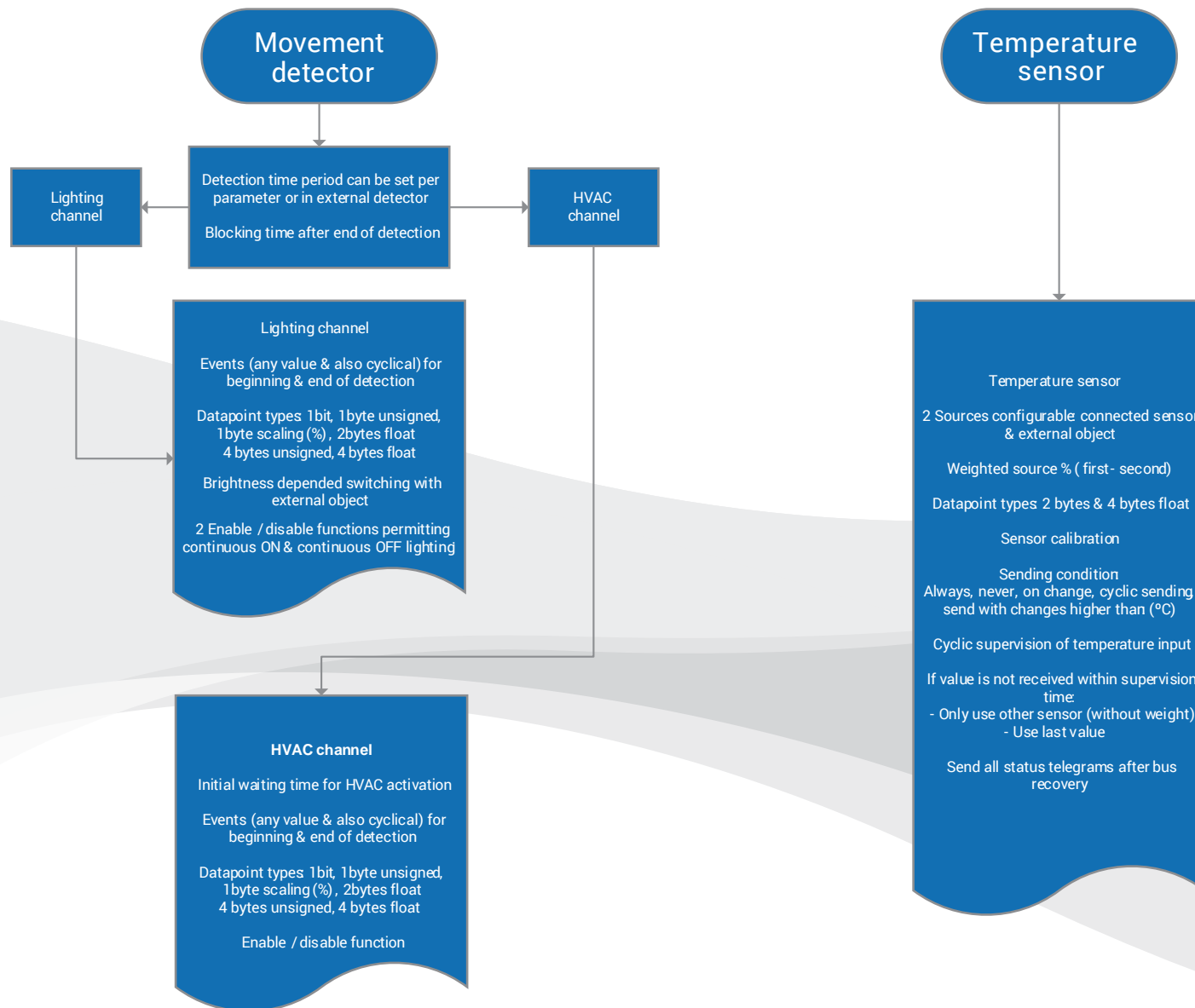


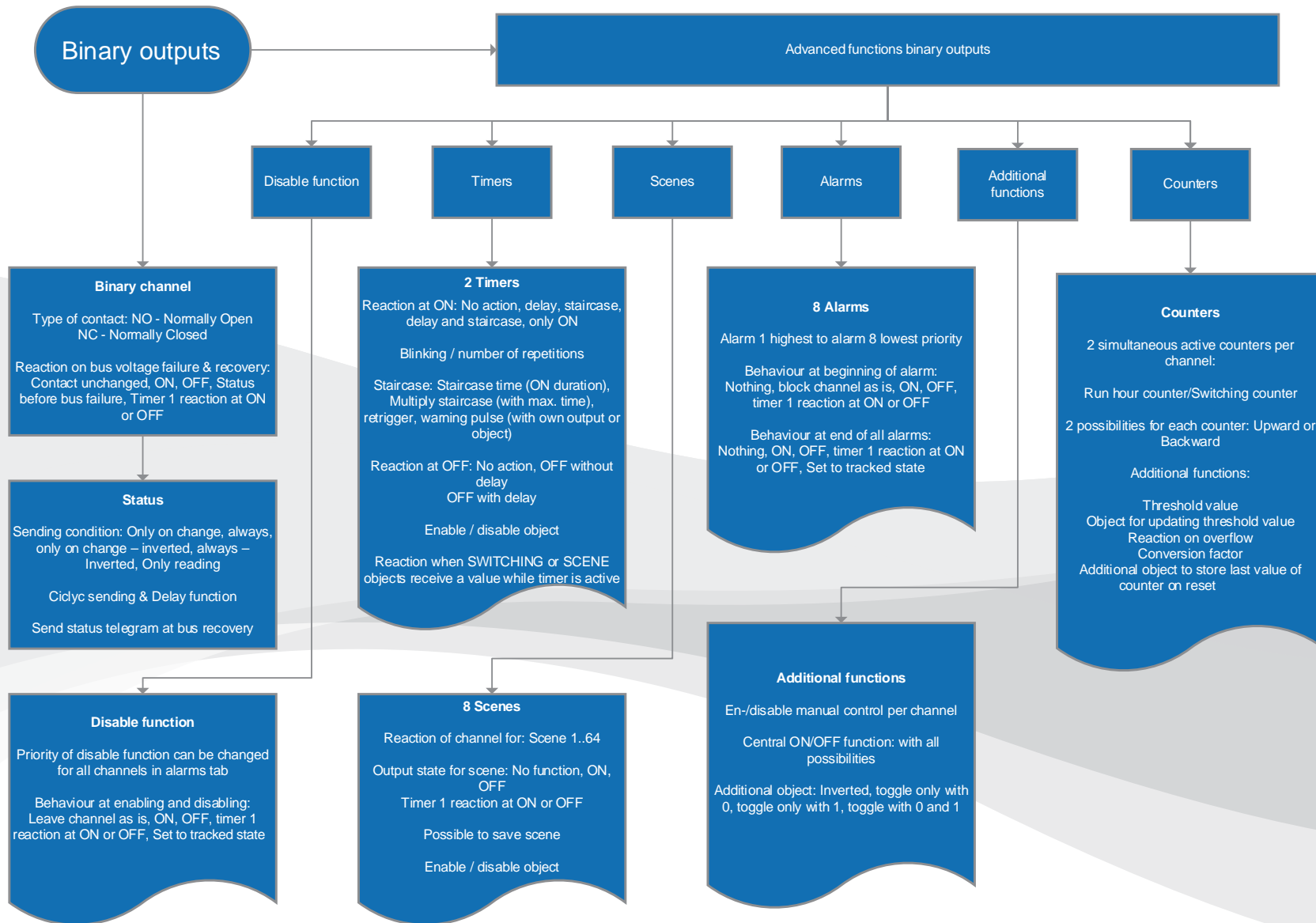


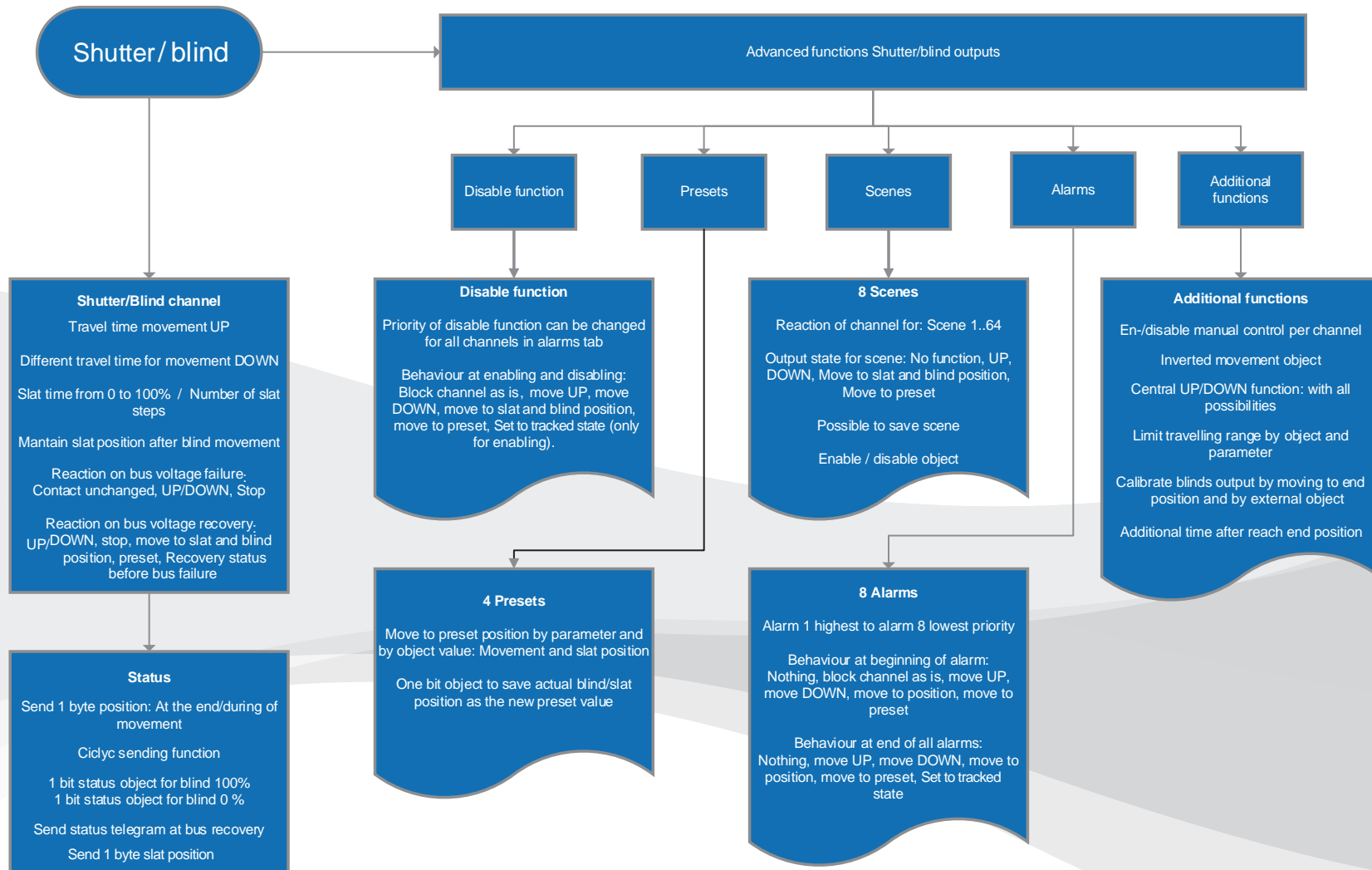
µBrick Series
ETS Application Program Flowchart

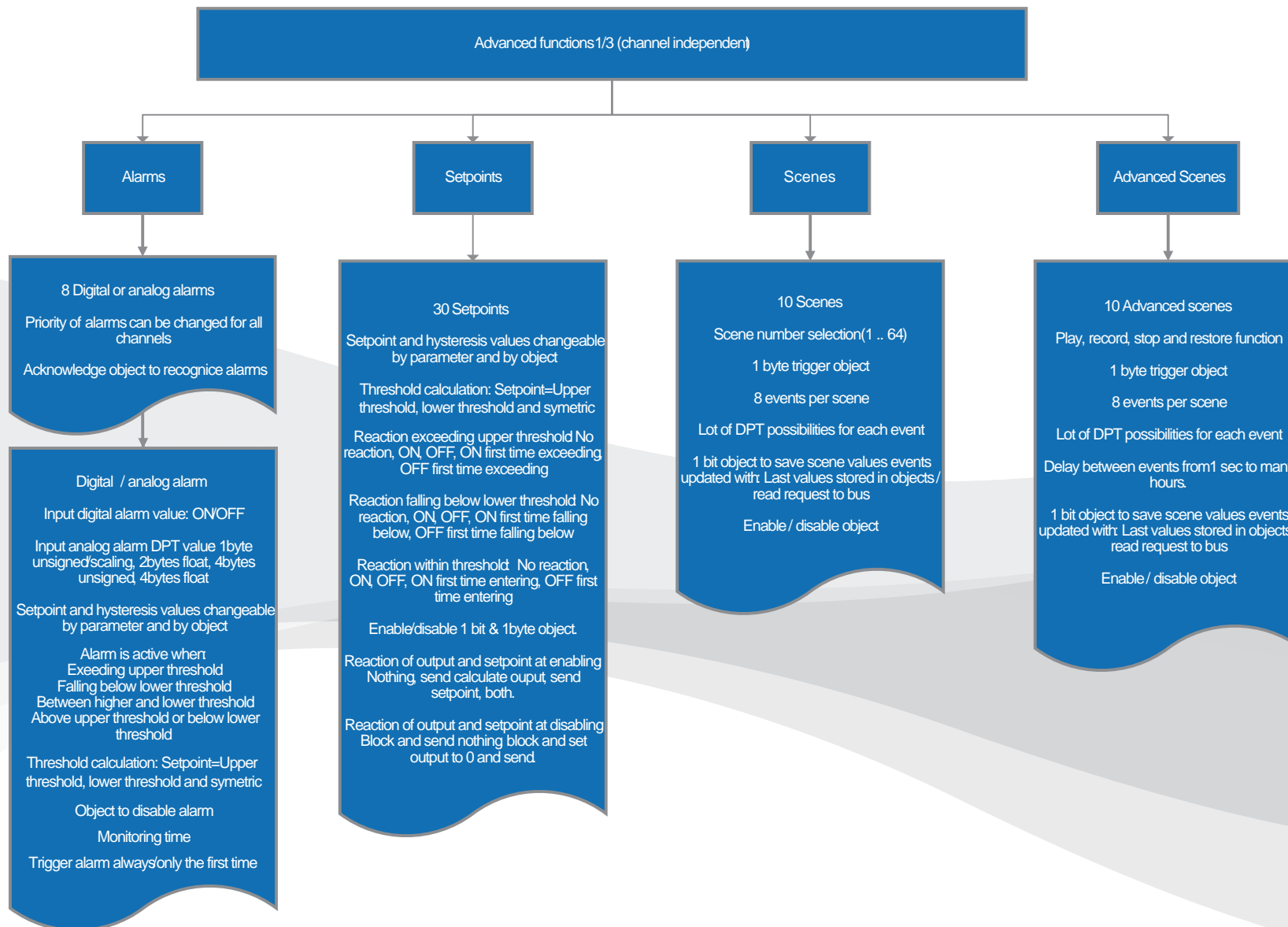


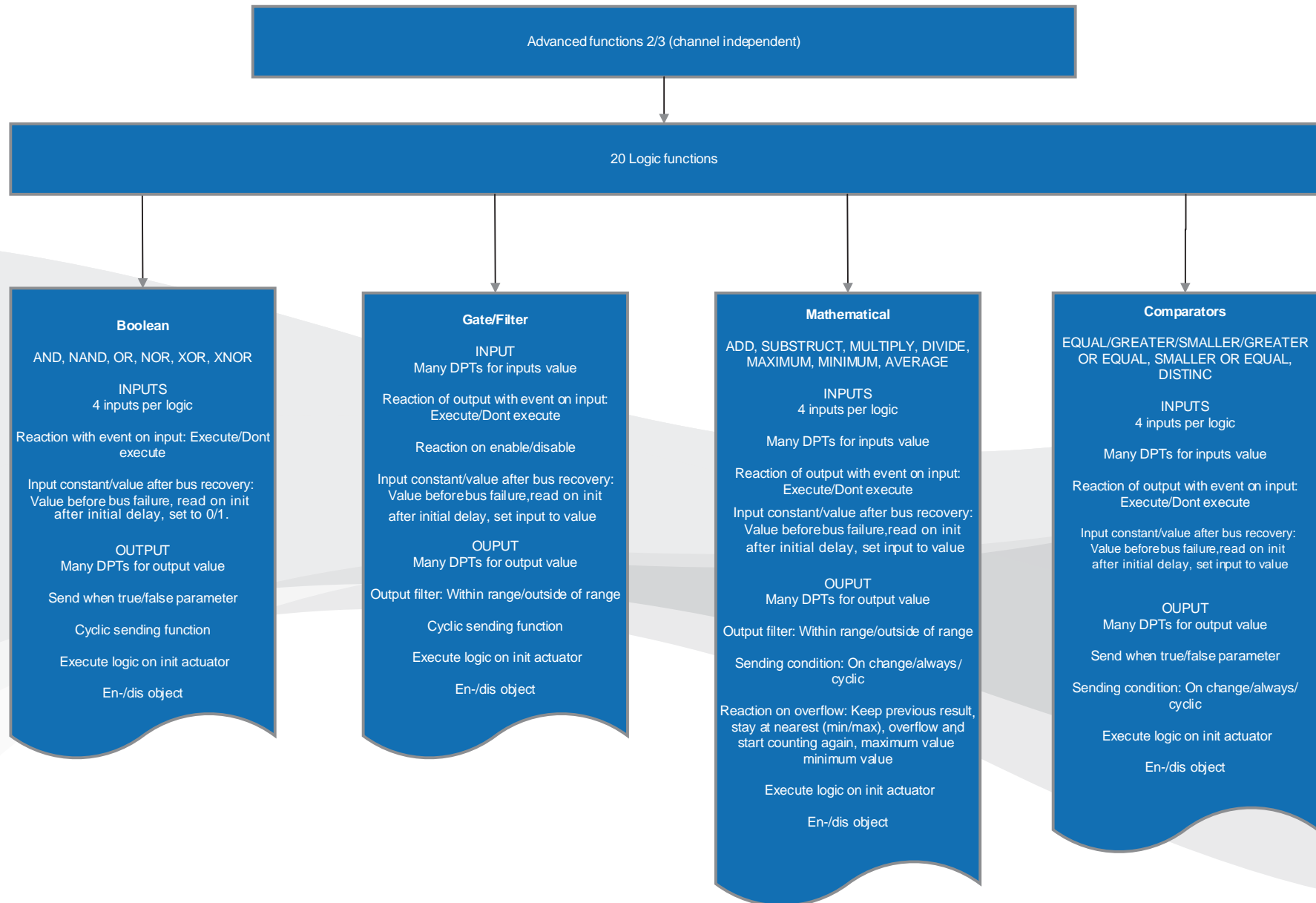












Advanced functions 3/3 (channel independent)

Timers

20 Logic functions

2 Timers

Reaction at ON: No action, delay, staircase, delay and staircase, only ON

Blinking / number of repetitions

Delay: Delay of any kind DPT telegram received.

Staircase: Staircase time (ON duration), Multiply staircase (with max. time), retrigger, warning pulse (with own output or object)

Reaction at OFF: No action, OFF without delay, OFF with delay

Enable / disable object

Converters

INPUT
Many DPTs for input value

Input constant / value after bus recovery: Value before bus failure, read on init after initial delay, set input to value.

OUTPUT
Many DPTs for output value

When result value exceeds max. allowed DPT output value: Don't send, send max value of output, send value.

When result value is lower than allowed DPT output value: Don't send, send min value of output, send absolute value, send value.

Output filter: Within range/outside of range

Cyclic sending function

Execute logic on init actuator

En-/dis object

Overwrite end-user parameters

Overwrite end-user parameters at download configured independent in each module:

ADVANCED FUNCTIONS
Alarms, scenes controller, advanced scene controller, timers, setpoints

OUTPUT CHANNELS
Channel A (A1, A2), channel B (B1, B2), ... channel I (I1, I2)

It is possible to configure in each one: Overwrite complete module, overwrite individually, don't overwrite.

Behaviour at bus recovery

Central cyclic sending for monitoring device

Send telegram on init for external use

Delay for sending all status telegrams

Delay between status telegrams

Delay for all initial read request and execute on init commands